

DESCRIPTION

ULTRASONIC DIAGNOSTIC APPARATUS

Technical Field

5 The present invention relates to an ultrasonic diagnostic apparatus having a function of determining a state of a blood vessel by ultrasonic waves.

Background Art

10 It is known as a function of ultrasonic diagnostic apparatuses that ultrasonic pulses are transmitted from a surface of a skin of a subject toward a blood vessel of the subject, so as to carry out a measurement on various states of the blood vessel based on ultrasonic echo signals reflected by the blood vessel.

15 For example, a method of detecting the boundary of a blood vessel wall by ultrasonic waves is disclosed in JP 2000-271117 A. According to this method, assuming that a blood vessel has a standard structure, the displacement and diameter of a blood vessel, the thickness of a blood vessel wall, and the like are measured based on a maximum peak value and a second peak value of a luminance signal in image data obtained based on 20 ultrasonic waves reflected by the blood vessel.

Further, a method of calculating a propagation speed of pulse waves in a blood vessel is disclosed in JP 11(1999)-76233 A. According to this method, a propagation speed of pulse waves is determined based on a variation with time in the cross-sectional shape of a blood vessel in a plurality 25 of regions in a longitudinal direction of the blood vessel.

Further, Japanese Patent No. 2889568 discloses a method of detecting an IMT (Intima-Media Thickness) value of a blood vessel wall (carotid artery) by ultrasonic waves. According to this method, assuming that a blood vessel has a standard structure, an IMT value of a blood vessel

wall (carotid artery) is measured based on a maximum peak value and a second peak value of a luminance signal in image data obtained based on ultrasonic waves reflected by the blood vessel.

However, in an actual medical diagnosis of a blood vessel, it is
5 difficult in many cases to carry out a measurement in a stable state due to a variety of factors such as a state in which an ultrasonic probe is fixed, a stationary and respiratory state of a subject, and the like.

On this account, in an actual measurement, a large-scale device is used to fix a probe and a subject and the subject is requested to stop his/her
10 breathing during the measurement, so that a measurement is more likely to be carried out stably. Further, the measurement is carried out a plurality of times and data that can be measured with accuracy are selected.

Consequently, the measurement takes a long diagnosis time, and a constant measurement accuracy cannot be obtained by different operators. Also, for
15 future use in the area of a diagnosis targeted for a large number of people, such as a medical examination, means for judging a state of stability of a measurement is being demanded.

Disclosure of Invention

20 An object of the present invention is to provide an ultrasonic diagnostic apparatus that is capable of judging a state of stability of a measurement.

An ultrasonic diagnostic apparatus according to the present invention includes: transmission means for transmitting at least one ultrasonic signal
25 from a surface of a skin of a subject toward a blood vessel of the subject; reception means for receiving an ultrasonic echo reflected by the blood vessel and converting the ultrasonic echo into an electric signal to obtain the ultrasonic echo signal in a depth direction from the surface of the skin; movement detection means for analyzing a phase of the ultrasonic echo signal
30 in a direction traversing the blood vessel to calculate a movement amount in

each of a plurality of regions including a blood vessel wall composing the blood vessel and a vicinity of the blood vessel wall; analysis means for analyzing a state of the blood vessel based on a variation in the calculated movement amount in each of the regions; boundary position detection means 5 for detecting a boundary position between a blood flow region and the blood vessel wall of the blood vessel based on a result of the analysis by the analysis means; and stability judgment means for comparing the boundary position detected by the boundary position detection means with a detection result in a previous cycle.

10 This configuration makes it possible to judge the stability of the detection of the boundary position based on a result of comparing the detected boundary position between the blood flow region and the blood vessel wall with a detection result in a previous cycle. Consequently, an operator easily and promptly can be notified whether measured data are 15 appropriate or not during a measurement.

Preferably, the above-mentioned configuration further includes an ROI (Region of Interest) positioning means for positioning an ROI where the boundary position in the depth direction from the surface of the skin is to be detected by the boundary position detection means, and the ROI positioning 20 means positions the ROI so that the ROI lies astride at least one of an anterior wall of the blood vessel wall on a side closer to the transmission means and a posterior wall of the blood vessel wall on a side farther from the transmission means. This configuration allows reliable detection of the boundary position between the blood vessel wall and the blood flow region.

25 Preferably, the transmission means transmits a plurality of ultrasonic signals toward a plurality of regions in a longitudinal direction of the blood vessel, the boundary position detection means detects the plurality of boundary positions in the longitudinal direction of the blood vessel, and the stability judgment means compares the plurality of boundary positions 30 detected by the boundary position detection means, thereby judging the

stability of a result of the detection of the boundary positions. This configuration allows the judgment accuracy to be increased.

In the above-mentioned configuration, the boundary position detection means can detect the plurality of boundary positions in the depth 5 direction from the surface of the skin, and a blood vessel diameter calculation means for calculating a diameter of the blood vessel based on the plurality of detected boundary positions further can be included. This configuration allows multifaceted detection of a state of the blood vessel.

The stability judgment means can compare the diameter of the blood 10 vessel calculated by the blood vessel diameter calculation means with a calculation result in a previous cycle, thereby judging the stability of a result of the detection of the boundary positions. This configuration allows stable detection of a state of the blood vessel.

The boundary position detection means can detect the boundary 15 positions in the plurality of regions in the longitudinal direction of the blood vessel, and a pulse wave propagation speed calculation means for calculating a pulse wave propagation speed indicating a speed at which a pulse wave propagates, based on a variation with time in the plurality of boundary positions detected by the boundary position detection means further can be 20 included. This configuration allows multifaceted detection of a state of the blood vessel.

The stability judgment means can compare the pulse wave propagation speed calculated by the pulse wave propagation speed calculation means with the pulse wave propagation speed calculated in a previous cycle, 25 thereby judging the stability of a result of the calculation of the pulse wave propagation speed. This configuration allows stable detection of the pulse wave propagation speed.

The pulse wave propagation speed calculation means can calculate pulse wave propagation speeds in a plurality of adjacent regions in the 30 longitudinal direction of the blood vessel, and the stability judgment means

can compare the pulse wave propagation speeds in the plurality of adjacent regions, thereby judging the stability of the calculation of the pulse wave propagation speeds by the pulse wave propagation speed calculation means. This configuration allows the judgment accuracy to be increased.

5 The boundary position detection means can detect a boundary position between a tunica intima and the blood flow region of the blood vessel and a position of a tunica media of the blood vessel based on a hardness value of tissue in the depth direction, and the stability judgment means can compare the boundary position and the position of the tunica media detected
10 by the boundary position detection means with the boundary position and the position of the tunica media calculated a predetermined number or more of cycles prior to the present cycle, thereby judging the stability of a result of the detection of the boundary position and the position of the tunica media. This configuration allows stable detection of the boundary position and the
15 position of the tunica media.

 The transmission means can transmit a plurality of ultrasonic signals toward a plurality of regions in the longitudinal direction of the blood vessel, the boundary position detection means can detect the boundary positions between the tunica intima and the blood flow region of the blood vessel and
20 the positions of the tunica media of the blood vessel in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means can compare the boundary positions and the positions of the tunica media adjacent to each other that are detected by the boundary position detection means, thereby judging the stability of the
25 detection of the boundary positions and the positions of the tunica media by the boundary position detection means. This configuration allows stable detection of the boundary position and the position of the tunica media.

 An IMT (Intima-Media Thickness) calculation means for measuring an IMT, which is a thickness from the tunica intima to the tunica media,
30 based on a variation with time in the boundary position between the tunica

intima and the blood flow region of the blood vessel and a variation with time in the position of the tunica media of the blood vessel further can be included, and the stability judgment means can judge the stability of a result of the detection of the boundary position by the boundary position detection means 5 based on the IMT measured by the calculation means. This configuration allows stable detection of the boundary position.

The IMT calculation means can calculate the IMT values in a plurality of regions adjacent to each other in the longitudinal direction of the blood vessel, and the stability judgment means can compare the IMT values 10 in the plurality of regions, thereby judging the stability of a result of the detection of the boundary position by the boundary position detection means. This configuration allows stable detection of the boundary position.

Display means for displaying the stability judged by the stability judgment means further can be included. This configuration allows visual 15 recognition of the stability.

Brief Description of Drawings

Figure 1 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a first embodiment of the present 20 invention.

Figure 2 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus shown in Figure 1.

Figure 3 is a schematic view for explaining another operation of the ultrasonic diagnostic apparatus shown in Figure 1.

25 Figure 4 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a second embodiment of the present invention.

Figure 5 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus shown in Figure 4.

Description of the Invention

Hereinafter, embodiments of the present invention will be described with reference to the drawings.

(First Embodiment)

5 Figure 1 is a block diagram schematically showing a configuration of an ultrasonic diagnostic apparatus according to a first embodiment of the present invention. Note here that Figure 1 also shows a B-mode image 20 received by the ultrasonic diagnostic apparatus. A transmission unit 1 generates an ultrasonic pulse and supplies it to an ultrasonic probe 2. The 10 ultrasonic probe 2 transmits the ultrasonic pulse supplied from the transmission unit 1 from a surface of a skin of a living body toward the inside thereof. The B-mode image 20 is an image obtained when the ultrasonic pulse is transmitted toward a blood vessel 21.

15 In this image, the blood vessel 21 extends in a direction tilted with respect to the surface of the skin and is indicated by an anterior wall 23a and a posterior wall 23b that surround a blood flow region 22 in the lumen in which blood flows. The anterior wall 23a is a blood vessel wall on a side closer to the ultrasonic probe 2, and the posterior wall 23b is a blood vessel wall on a side farther from the ultrasonic probe 2. In this example, the blood 20 vessel 21 has an atheroma 24 as a local disease that is developed on an inner surface of the posterior wall 23b.

25 The blood vessel wall shown as the anterior wall 23a and the posterior wall 23b includes a tunica intima 25 that is formed on an inner surface of the blood vessel wall and faces the blood flow region 22, a tunica adventitia 26 formed on an outer surface of the blood vessel wall, and a tunica media 27 formed between the tunica intima 25 and the tunica adventitia 26. In Figure 8, the atheroma 24 as a local disease is developed between the tunica intima 25 and the tunica media 27.

30 An ultrasonic echo reflected by the blood vessel 21 is converted into an electric signal by the ultrasonic probe 2, and the obtained ultrasonic echo

signal is supplied to a movement detection unit 5 on one hand via a reception unit 3 and a delay synthesis unit 4. The movement detection unit 5 detects a movement amount in each region in a depth direction from the surface of the skin based on the received ultrasonic echo signal. The detection of a 5 movement amount in each region by the movement detection unit 5 can be carried out by a well-known method based on a phase change of the received signal, and thus a specific description will be omitted.

In the B-mode image 20, an ROI (Region of Interest) 25 is shown that is provided for detecting a boundary position in the depth direction from the 10 surface of the skin. The positioning of the ROI 28 in a tomographic image is set by an ROI positioning unit 6. In order to achieve the object of the present embodiment, the ROI 28 is set so as to lie astride at least one of the anterior wall 23a and the posterior wall 23b. In the example shown in Figure 1, the ROI 28 is positioned so as to lie astride both the anterior wall 15 23a and the posterior wall 23b.

The movement amount detected by the movement detection unit 5 is supplied to a hardness value conversion unit 7. The hardness value conversion unit 2 converts the movement amount detected by the movement detection unit 5 into a hardness value of tissue in the depth direction from the 20 surface of the skin. For example, when a difference in the movement amount (thickness variation) between neighboring regions is analyzed from a variation in the movement amount in respective regions of the blood vessel wall, a large thickness variation is obtained in a soft region, while a small thickness variation is obtained in a hard region. Thus, based on this, the 25 hardness value in each region can be detected. The hardness value of the tissue obtained by the hardness value conversion unit 7 is supplied to a boundary position detection unit 8.

The boundary position detection unit 8 detects a boundary position between the tunica intima 25 and the blood flow region 22 of the blood vessel 30 21 and a position of the tunica media 27 based on the hardness value. Since

the detection is carried out based on the hardness value of the tissue in the depth direction, by which a variation state of the tissue is clarified, the boundary position can be recognized automatically with a simple algorithm. Further, the boundary position detection unit 8 generates a

5 two-dimensionally mapped color display image showing a cross section of the blood vessel 21, and supplies it to an image synthesis unit 9.

Instead of the hardness value conversion unit 7, a method of analyzing another state of the blood vessel based on the movement amount detected by the movement detection unit 5 may be used, so that the boundary

10 position detection unit 8 can detect the boundary position based on a result of that analysis. For example, when attention is given to a variation state (track) of the movement amount of the blood vessel in one heartbeat, the track has different characteristics such as a movement direction reversed between the blood flow region 22 and the posterior wall 23b. Thus, by

15 analyzing this, a middle point at which the track is reversed can be judged as the boundary position 25.

The received signal that has passed through the reception unit 3 and the delay synthesis unit 4 is supplied also to a B-mode processing unit 10 on the other hand. The B-mode processing unit 10 generates image

20 information showing the cross section of the blood vessel 21 based on the received signal, and supplies it to the image synthesis unit 9. The image synthesis unit 9 synthesizes the image information supplied from the B-mode processing unit 10 and the boundary information recognized automatically by the boundary position detection unit 8, and displays the synthesis on a

25 monitor of a display unit 11.

The detection signal from the boundary position detection unit 8 is supplied also to a blood vessel diameter calculation unit 12, a pulse wave propagation speed calculation unit 13, an IMT calculation unit 14, and a stability judgment unit 15.

30 The blood vessel diameter calculation unit 12 calculates a diameter of

the lumen of the blood vessel 21 based on a plurality of boundary positions recognized automatically by the boundary position detection unit 8. The pulse wave propagation speed calculation unit 13 calculates a pulse wave propagation speed indicating a speed at which a pulse wave propagates, 5 based on a variation with time in the plurality of boundary positions recognized automatically by the boundary position detection unit 8. More specifically, the boundary position detection unit 8 detects the boundary positions in a plurality of regions in a longitudinal direction of the blood vessel, and supplies them to the pulse wave propagation speed calculation 10 unit 13. The pulse wave propagation speed calculation unit 13 calculates a pulse wave propagation speed based on a variation with time in the plurality of boundary positions. A specific method of the calculation is disclosed in JP 11(1999)-76233 A.

The IMT calculation unit 14 uses the detection signal output from the 15 boundary position detection unit 8 to measure the thickness of the tunica media 27 as an IMT value based on a variation with time in the boundary position between the tunica intima 25 and the blood flow region 22 and a variation with time in the position of the tunica media 27 in one heartbeat cycle. The IMT calculation unit 14 calculates at least one of a maximum 20 value, a minimum value, and an average value of the IMT value in one heartbeat cycle.

The outputs from the blood vessel diameter calculation unit 12, the pulse wave propagation speed calculation unit 13, and the IMT calculation unit 14 are supplied to a stability judgment unit 15. The stability judgment 25 unit 15 has a function of judging the stability of a measurement. The stability judgment unit 15 is supplied with the detection signals from the movement detection unit 5 and the boundary position detection unit 8 and judges the stability based on those signals. For example, the stability judgment unit 15 compares the movement amount of the blood vessel wall 30 calculated by the movement detection unit 5 with the movement amount of

the blood vessel wall calculated a predetermined number or more of cycles prior to the present cycle, thereby judging the stability of the result of the detection of the movement amount of the blood vessel wall by the movement detection unit 5. A detailed operation thereof will be described later.

5 Figure 2 is a schematic view for explaining an operation of the ultrasonic diagnostic apparatus according to the present embodiment. In Figure 2, (a) shows an image that is the same as the B-mode image 20 shown in Figure 1. Reference numeral 29 denotes a single scanning line indicating a track of an ultrasonic wave transmitted from the ultrasonic probe 2. In 10 the figure, (b) shows a hardness value 27 of the tissue that is obtained by the hardness value conversion unit 7 for each portion on the scanning line 29.

15 Herein, attention is given to a point R0 on the tunica intima 25 of the anterior wall 23a on a side closer to the surface of the skin, a point R1 on the tunica intima 25 of the posterior wall 23b on a side farther from the surface of the skin, and a point R2 on the tunica media 27 of the posterior wall 23b on 20 the scanning line 29. The point R0 is located at a position at a depth Dt from the surface of the skin, the point R1 is located at a position at a depth Db from the surface of the skin, and the point R2 is located at a position at a depth Di from the surface of the skin. The hardness value at the points R0, R1, and R2 is represented by E0, E1, and E2, respectively, in (b).

25 The hardness value 30 in the depth direction from the surface of the skin is far lower in the blood flow region 22 than on the blood vessel wall. On this account, based on the hardness value 30, the boundary position between the blood flow region 22 and the tunica intima 25 easily can be recognized automatically with a simple algorithm.

 In addition, the inner diameter of the blood vessel can be calculated by the following Formula (1), and the IMT value can be calculated automatically by incorporating the following Formula (2) into an algorithm.

$$\text{Inner diameter of blood vessel} = Db - Dt \quad \dots (1)$$

30 IMT = Di - Db \dots (2)

Herein, $Di - Db$ corresponds to the thickness from the tunica intima to the tunica media.

Further, when the transmission unit 3 transmits a plurality of ultrasonic signals toward a plurality of regions in the longitudinal direction of 5 the blood vessel 21, and the same processing as above is performed with respect to a plurality of scanning lines 29 corresponding to a plurality of ultrasonic echo signals, it is possible to obtain distributions of the propagation speed of a pulse wave, the hardness value, and the like in the longitudinal direction of the blood vessel 21.

10 Next, the operation of the stability judgment unit 15 will be described with reference to Figure 3. As mentioned above, in an actual medical diagnosis of a blood vessel, it is difficult to carry out a measurement in a stable state due to a variety of factors such as a state in which the ultrasonic probe 2 is fixed, a stationary and respiratory state of a subject, and the like. 15 Consequently, in reality a large-scale device is used to fix the probe 2 and a subject and the subject is requested to stop his/her breathing during a measurement, so that a measurement is more likely to be carried out stably. Further, the measurement is carried out a plurality of times and data that can be measured with accuracy are selected. As a result, the measurement 20 takes a long diagnosis time, and moreover a constant measurement accuracy cannot be obtained by different operators.

When ideal measured data are obtained in a state in which the positional relationship between a subject and the ultrasonic probe 2 is constant or a state in which the subject is in a stable state by stopping his/her 25 breathing, the blood vessel wall has a closely analogous movement track during each heartbeat. Based on this, the stability of the measurement for detecting the IMT value itself is judged.

Figure 3 is a schematic view for explaining the operation of the stability judgment unit 15. In the figure, (a) shows an ECG 30 (Electrocardiograph) waveform 28. Waveforms shown in (b) to (d) indicate

movement tracks 32, 33, and 34, respectively, of the blood vessel wall in respective measuring cycles synchronized with a heartbeat cycle of the ECG waveform 31 shown in (a). The movement track 32 shown in (b) is measured in a cycle immediately preceding the cycles in which the movement tracks 33
5 and 34 shown in (c) and (d) are measured.

In (b) of Figure 3, a tolerance 33 is shown that allows for a permissible error 35 with respect to the movement track 32 in the immediately preceding cycle. The tolerance 36 is compared with a movement track in the subsequent measuring cycle. For example, in the
10 case of the movement track 30 shown in (c) that is within the tolerance 36 at any points, it is judged that a stable measurement has been carried out. In the case of the movement track 31 shown in (d) that has improper points 37 out of the tolerance 36, it is judged that a measurement has been carried out unstably.

15 When an operator is notified of information indicating whether a measurement has been carried out stably or unstably in real time, the operator can judge during the measurement whether the present measurement result is reliable or not. Consequently, a measuring time can be made shorter.

20 Further, the stability judgment unit 15 can compare the boundary position between the blood flow region 22 and the tunica intima 25 and the position of the tunica media 27 that are detected by the boundary position detection unit 8 with the boundary position and the position of the tunica media 27 calculated a predetermined number or more of cycles prior to the
25 present cycle, thereby judging the stability of the result of the detection of the boundary position and the position of the tunica media 27.

Further, the stability judgment unit 15 may judge whether a measurement has been carried out stably or unstably based on a difference between the measurement result in the present cycle and that in the
30 immediately preceding cycle. Alternatively, the stability judgment unit 15

may judge whether a measurement has been carried out stably or unstably based on a comparison with stable movement tracks measured not only in the immediately preceding cycle but also in a plurality of past cycles. Further, the threshold value (permissible error 35) for the judgment as to whether a 5 measurement has been carried out stably or unstably may be changed.

Further, the boundary position detection unit 8 can detect a plurality of boundary positions in the longitudinal direction of the blood vessel 21, and the stability judgment unit 15 can compare the plurality of boundary positions detected by the boundary position detection unit 8, thereby judging 10 the stability of the result of the detection of the boundary positions.

In the present embodiment, the stability judgment unit 15 also can judge the stability of a measurement based on the output from the blood vessel diameter calculation unit 12, the pulse wave propagation speed calculation unit 13, or the IMT calculation unit 14 in the following manner. 15 For example, the stability judgment unit 15 compares the diameter of the blood vessel calculated by the blood vessel diameter calculation unit 12 with a calculation result in a previous cycle, thereby judging the stability of the result of the detection of the boundary position between the blood flow region 22 and the tunica intima 25. Alternatively, the stability judgment unit 15 20 compares the pulse wave propagation speed calculated by the pulse wave propagation speed calculation unit 13 with that calculated in a previous cycle, thereby judging the stability of the result of the calculation of the pulse wave propagation speed. Alternatively, the pulse wave propagation speed calculation unit 13 calculates pulse wave propagation speeds in a plurality of 25 adjacent regions in the longitudinal direction of the blood vessel, and the stability judgment unit 15 compares the pulse wave propagation speeds in the plurality of adjacent regions, thereby judging the stability of the result of the calculation of the pulse wave propagation speeds. Alternatively, the IMT calculation unit 14 calculates IMT values in a plurality of regions adjacent to 30 each other in the longitudinal direction of the blood vessel 21, and the

stability judgment unit 15 compares the IMT values in the plurality of regions, thereby judging the stability of the result of the detection of the boundary position by the boundary position detection unit 6.

Further, the stability judgment unit 15 may compare a value of, for 5 example, pseudo boundary judgment position, which is obtained from an echo brightness value unsuitable for judging a boundary, in the present cycle with that in the immediately preceding cycle. By combining a plurality of such functions of judging the measurement stability, the reliability of a measurement result can be increased further.

10

(Second Embodiment)

Figure 4 is a block diagram showing a configuration of an ultrasonic diagnostic apparatus according to a second embodiment. Components common to those of the ultrasonic diagnostic apparatus according to the first 15 embodiment shown in Figure 1 are denoted with the same reference numerals, and repeated descriptions will be omitted.

In the present embodiment, a stability judgment unit 15A has a different configuration from that of the stability judgment unit 15 in Figure 1. The stability judgment unit 15A compares boundary positions and positions 20 of the tunica media adjacent to each other in a direction traversing the blood vessel 21, the positions being detected by the boundary position detection unit 8, thereby judging the stability of the detection of the boundary positions and the positions of the tunica media by the boundary position detection unit 8.

Figure 5 is a schematic view for explaining an operation of the 25 ultrasonic diagnostic apparatus according to the present embodiment. In Figure 5, (a) shows a cross section 38 of the blood vessel. A measurement is performed such that three scanning lines 39a, 39b, and 39c pass through the cross section 38 of the blood vessel. In the Figure, (b) to (d) show hardness values 40a, 40b, and 40c measured by the scanning lines 39a, 39b, and 39c, 30 respectively.

With respect to the hardness value 40b corresponding to the scanning line 39b that passes exactly through the center of the blood vessel, an ultrasonic echo signal has a clearer intensity difference because an ultrasonic signal impinges upon a wall surface and a film surface almost vertically.

5 Thus, a clear peak waveform 41 for separating the tunica intima 25 and the tunica media 27 is obtained. On the other hand, with respect to the hardness values 40a and 40c corresponding to the scanning lines 39a and 39c, respectively, that do not pass exactly through the center of the blood vessel, the ultrasonic echo signal has an unclear intensity difference on the wall
10 surface and the film surface, and waveforms 42 and 43 do not have their peaks. Consequently, it is difficult to separate the tunica intima 25 and the tunica media 27, and the IMT value cannot be obtained.

With the use of such characteristics of the hardness value, when the IMT value can be measured stably, it is possible to judge whether a path of
15 the ultrasonic wave indicated by the scanning line is exactly through the center of the cross section of the blood vessel. Thus, the stability of a measurement itself by the ultrasonic diagnostic apparatus can be judged.

Further, the stability of the measurement can be judged by simultaneously referring to the results of the measurement of the IMT values
20 in a plurality of regions in the direction traversing the blood vessel. Further, in combination with a comparison with the IMT value in the immediately preceding cycle or the like, the reliability of the measurement can be increased further.

As described above, the stability (constancy) of a measurement itself
25 can be judged based on the fact that the center of the cross section of the blood vessel has to be captured at all times when the IMT value is measured.

Further, when an operator is notified of information indicating the stability (constancy) of a measurement itself in real time, the operator can judge during the measurement whether the present measurement result is
30 reliable or not. Consequently, a measuring time can be made shorter.

Industrial Applicability

According to the present invention, it is possible to provide the ultrasonic diagnostic apparatus that is capable of judging a state of stability of a measurement.